

Comparing Scale Parameter Estimators for Gaussian Process Regression: Cross Validation and Maximum Likelihood

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Probabilistic Numerics Spring School 2024, Southampton UK

Outline

- 1 Introduction and Background
- 2 Contributions and Problem Setting
- 3 Main Results on Asymptotics
- 4 Consequences to Credible Intervals
- 5 Conclusion and Future Directions

Gaussian Process (GP) Interpolation

- Given training data $(x_1, f(x_1)), \dots, (x_N, f(x_N))$, estimate the **unknown data-generating function** $f(x)$.
- By specifying a GP prior $f \sim GP(0, k)$ as with kernel k , GP interpolation produces the GP posterior of f with **posterior mean** $m_N(x)$ and **posterior covariance** $k_N(x, x')$:

$$m_N(x) := k(x, \mathbf{x})^\top k(\mathbf{x}, \mathbf{x})^{-1} f(\mathbf{x}), \quad (1a)$$

$$k_N(x, x') := k(x, x') - k(x, \mathbf{x})^\top k(\mathbf{x}, \mathbf{x})^{-1} k(\mathbf{x}, x'), \quad (1b)$$

where

$$\mathbf{x} := [x_1, \dots, x_N]^\top, \quad f(\mathbf{x}) := [f(x_1), \dots, f(x_N)]^\top \in \mathbb{R}^N,$$

$$k(x, \mathbf{x}) := [k(x, x_1), \dots, k(x, x_N)]^\top \in \mathbb{R}^N, \quad k(\mathbf{x}, \mathbf{x}) := (k(x_i, x_j)) \in \mathbb{R}^{N \times N}.$$

Gaussian Process (GP) Interpolation

- Posterior mean $m_N(x)$ is used for predicting $f(x)$.
- **Posterior variance** $k_N(x) := k_N(x, x)$ is used for **uncertainty quantification (UQ)** of $f(x)$.
- Many applications: Probabilistic numerics, Bayesian optimization, etc.

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Challenge: Hyper Parameter Selection

- Both prediction and UQ performance depend on the choice of **kernel parameters** (or the kernel itself).
- This talk focuses on **UQ performance**.

Credible Intervals

- For a constant $\alpha > 0$, a credible interval for $f(x)$ can be defined as

$$[m_N(x) - \alpha\sqrt{k_N(x)}, \quad m_N(x) + \alpha\sqrt{k_N(x)}].$$

(e.g., $\alpha \approx 1.96$ for a 95 % credible interval.)

- We want the interval to include the true $f(x)$, i.e.,

$$\begin{aligned}
 m_N(x) - \alpha\sqrt{k_N(x)} &\leq f(x) \leq m_N(x) + \alpha\sqrt{k_N(x)} \\
 &\Downarrow \\
 -\alpha &\leq \frac{f(x) - m_N(x)}{\sqrt{k_N(x)}} \leq +\alpha
 \end{aligned}$$

Asymptotically Well-calibrated Credible Intervals

$$-\alpha \leq \frac{f(x) - m_N(x)}{\sqrt{k_N(x)}} \leq +\alpha$$

- Therefore, for the interval to be well-calibrated, the posterior std $\sqrt{k_N(x)}$ and the prediction error $|f(x) - m_N(x)|$ should decrease to 0 at the **same speed** as $N \rightarrow \infty$.

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- If $\sqrt{k_N(x)} \rightarrow 0$ **faster** than $|f(x) - m_N(x)| \rightarrow 0$, then the interval will **not contain** the true $f(x)$ as $N \rightarrow \infty$ (**overconfident**).

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- If $\sqrt{k_N(x)} \rightarrow 0$ **slower** than $|f(x) - m_N(x)| \rightarrow 0$, then the interval will get **looser** as $N \rightarrow \infty$ (**underconfident**).

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 - If $\sqrt{k_N(x)} \rightarrow 0$ **faster** than $|f(x) - m_N(x)| \rightarrow 0$, then the interval will **not contain** the true $f(x)$ as $N \rightarrow \infty$ (**overconfident**).
 - If $\sqrt{k_N(x)} \rightarrow 0$ **slower** than $|f(x) - m_N(x)| \rightarrow 0$, then the interval will get **looser** as $N \rightarrow \infty$ (**underconfident**).
- If $\sqrt{k_N(x)} \rightarrow 0$ and $|f(x) - m_N(x)| \rightarrow 0$ at the **same speed**, we say the interval is **asymptotically well-calibrated**.

The Issue

- The issue is that, the posterior variance $k_N(x)$ does **not depend** on observations $f(x_1), \dots, f(x_N)$.

$$k_N(x) = k(x, x) - k(x, \mathbf{x})^\top k(\mathbf{x}, \mathbf{x})^{-1} k(\mathbf{x}, x),$$

- Thus, $\sqrt{k_N(x)}$ does **not decay at the same rate** as $|f(x) - m_N(x)|$ in general.
 - Exception: when the prior $f \sim \mathcal{GP}(0, k)$ is correct (well-specified).
 - But in general $f \sim \mathcal{GP}(0, k)$ **cannot be perfectly correct** (misspecified).

Examples

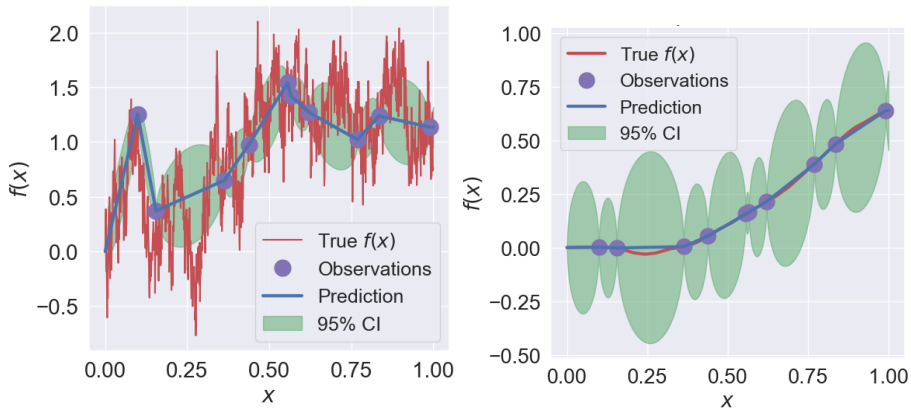


Figure 1: Left: when true f is coarser. Right: when true f is smoother.

Scale Parameter

- To address the above issue, one must adapt the kernel k to the data $f(x_1), \dots, f(x_N)$.
- A simple way is to introduce a **scale parameter** $\sigma^2 > 0$, parameterize the kernel as

$$k_\sigma(x, x') := \sigma^2 k(x, x').$$

and estimate σ^2 from the data $f(x_1), \dots, f(x_N)$.

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and estimate σ^2 from the data $f(x_1), \dots, f(x_N)$.

- We discuss two estimators for the scale parameter σ^2 : **Maximum Likelihood (ML)** and **Cross Validation (CV)**.

- ML: maximizing the **marginal likelihood**.
- CV: maximizing the **held-out (log) likelihood**, averaged over CV splits.

ML and CV Estimators for the Scale Parameter

- For the scale parameter, both ML and CV estimators can be derived analytically (and can be computed in $O(N^3)$ time complexity).

ML estimator:

$$\hat{\sigma}_{\text{ML}}^2 = \frac{f(\mathbf{x})^\top k(\mathbf{x}, \mathbf{x})^{-1} f(\mathbf{x})}{N} = \frac{1}{N} \sum_{n=1}^N \frac{[f(x_n) - m_{n-1}(x_n)]^2}{k_{n-1}(x_n)},$$

where m_{n-1} and k_{n-1} are the posterior mean and variance functions based on the first $n-1$ training observations $(x_1, f(x_1)), \dots, (x_{n-1}, f(x_{n-1}))$.

Leave-one-out (LOO) CV estimator:

$$\hat{\sigma}_{\text{CV}}^2 = \frac{1}{N} \sum_{n=1}^N \frac{[f(x_n) - m_{\setminus n}(x_n)]^2}{k_{\setminus n}(x_n)},$$

where $m_{\setminus n}$ and $k_{\setminus n}$ are the posterior mean and variance functions with $(x_n, f(x_n))$ removed: $\{(x_1, f(x_1)), \dots, (x_N, f(x_N))\} \setminus (x_n, f(x_n))$.

ML and CV Estimators for the Scale Parameter

$$\hat{\sigma}_{\text{ML}}^2 = \frac{1}{N} \sum_{n=1}^N \frac{[f(x_n) - m_{n-1}(x_n)]^2}{k_{n-1}(x_n)}, \quad \hat{\sigma}_{\text{CV}}^2 = \frac{1}{N} \sum_{n=1}^N \frac{[f(x_n) - m_{\setminus n}(x_n)]^2}{k_{\setminus n}(x_n)},$$

- The CV estimator uses **each data more evenly** than the ML estimator?

Questions:

- How does this difference affect their **asymptotic behaviours** as $N \rightarrow \infty$?
- Do these estimates give **asymptotically well-calibrated credible intervals**?
- Which one is **better in terms of UQ**?

(Closely) Related Work

- Most previous works consider **well-specified settings** where there exists a “true” scale parameter σ_0^2 ;
e.g., [Ying, 1991, Zhang, 2004, Bachoc et al., 2017, Bachoc et al., 2020].
- However, in general, there exists no such “true σ_0^2 ”.
- In such **misspecified settings**, both ML and CV estimators’ asymptotic properties are not well understood.
 - [Karvonen et al., 2020, Wang, 2021] derive upper bounds (and lower bounds in some cases) for the ML estimator (assuming deterministic f).
 - To our knowledge, there is no theoretical result for the CV estimator.
 - [Bachoc, 2013, Petit et al., 2022] empirically compare the ML and CV estimators under different model misspecification settings.

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Our Contributions

- This work analyses the asymptotic behaviours of the CV and ML estimators of the scale parameter.
 - This is the first analysis for the CV estimator.
 - We also obtain new results for the ML estimator.

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- This work analyses the asymptotic behaviours of the CV and ML estimators of the scale parameter.
 - This is the first analysis for the CV estimator.
 - We also obtain new results for the ML estimator.
- To facilitate the analysis, we focus on the following setting.
 - 1) **Noise-free observations (Interpolation):** $f(x_1), f(x_2), \dots, f(x_N)$.
 - 2) **Quasi-uniform input points:** $0 \leq x_1 < x_2 < \dots < x_N \leq 1$.

Problem Setting

3) **Brownian motion prior**: the kernel is

$$k(x, x') = \min(x, x'), \quad x, x' \in [0, 1].$$

- Then $f \sim \mathcal{GP}(0, k)$ is a Brownian motion.
- The **smoothness** of the model is $1/2$ (in terms of differentiability).

Problem Setting

4) True f 's smoothness is $0 < \ell + H < 2$. ($\ell \in \{0, 1\}, 0 < H < 1$):

- When $\ell = 0$ and $0 < H < 1$: We assume f to be a **fractional Brownian motion with Hurst parameter H** . We write $f_{FBM} \sim \mathcal{GP}(0, k_{0,H})$.¹

— **Smoothness H** . When $H = 1/2$, this is a standard Brownian motion.

¹ $k_{0,H}(x, x') = \frac{1}{2}(|x|^{2H} + |x'|^{2H} - |x - x'|^{2H})$

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— **Smoothness H** . When $H = 1/2$, this is a standard Brownian motion.

- When $\ell = 1$ and $0 < H < 1$: We define f as the integral of $f_{FBM} \sim \mathcal{GP}(0, k_{0,H})$ (i.e., an **integrated fractional Brownian motion**).

$$f_{iFBM}(x) = \int_0^x f_{FBM}(t) dt.$$

— **Smoothness $1 + H$** .

¹ $k_{0,H}(x, x') = \frac{1}{2}(|x|^{2H} + |x'|^{2H} - |x - x'|^{2H})$

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Asymptotics of CV and ML Estimators ($\ell = 0, 0 < H < 1$)

Theorem (when $\ell = 0$ and $0 < H < 1$):

$$\mathbb{E}[\hat{\sigma}_{\text{CV}}^2] = \Theta(N^{1-2H}), \quad \mathbb{E}[\hat{\sigma}_{\text{ML}}^2] = \Theta(N^{1-2H}).$$

- CV and ML have the same asymptotic properties.

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- CV and ML have the same asymptotic properties.

When $0 < H < 1/2$: True f is rougher than the GP prior.

- $1 - 2H > 0 \implies \hat{\sigma}_{\text{CV}}^2, \hat{\sigma}_{\text{ML}}^2$ increase as N increases.
- \implies Correcting the small posterior var $k_N(x)$ (overconfidence)

- Recall that the posterior variance with the scale parameter is $\hat{\sigma}^2 k_N(x)$

When the True Function is Rougher ($\ell + H = 0.2$)

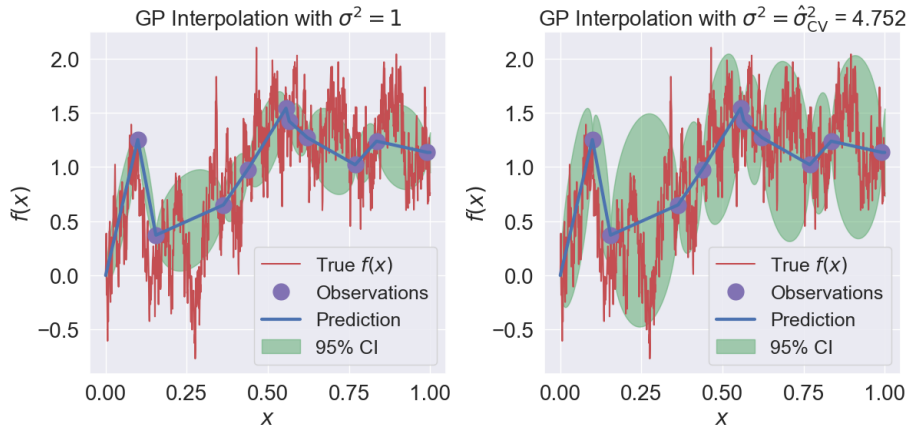


Figure 2: Left: no scale parameter; Right: with the CV estimator. (ML yields similar credible intervals.)

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When $H = 1/2$: The GP prior (Brownian motion) is well-specified.

- $1 - 2H = 0. \implies \hat{\sigma}_{\text{CV}}^2, \hat{\sigma}_{\text{ML}}^2$ converge to the “true value” σ_0^2 as $N \rightarrow \infty$ increases.

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When $1/2 < H < 1$: True f is **smoother** than the GP prior.

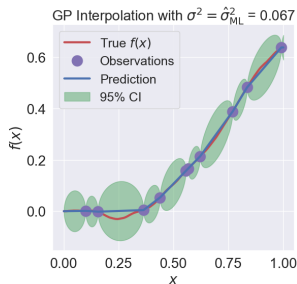
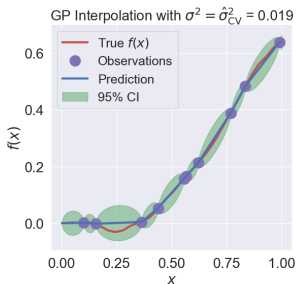
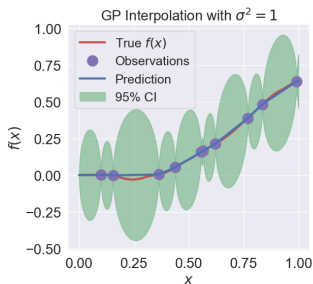
- $1 - 2H < 0. \implies \hat{\sigma}_{\text{CV}}^2, \hat{\sigma}_{\text{ML}}^2$ **decrease** as $N \rightarrow \infty$.
- **Correcting** the large posterior var $k_N(x)$ (underconfidence).

Asymptotics of CV and ML Estimators ($1 < \ell + H \leq 1.5$)

Theorem (when $\ell = 1$ and $0 < H \leq 0.5$):

$$\mathbb{E}[\hat{\sigma}_{\text{CV}}^2] = \Theta(N^{-1-2H}), \quad \mathbb{E}[\hat{\sigma}_{\text{ML}}^2] = \Theta(N^{-1}).$$

- CV **adapts** to the **true smoothness** $1 + H$ (correcting underconfidence).
- ML does **not adapt** (underconfidence not corrected \Rightarrow conservative credible intervals).



When the True Function is Smoother ($\ell + H = 1.5$)

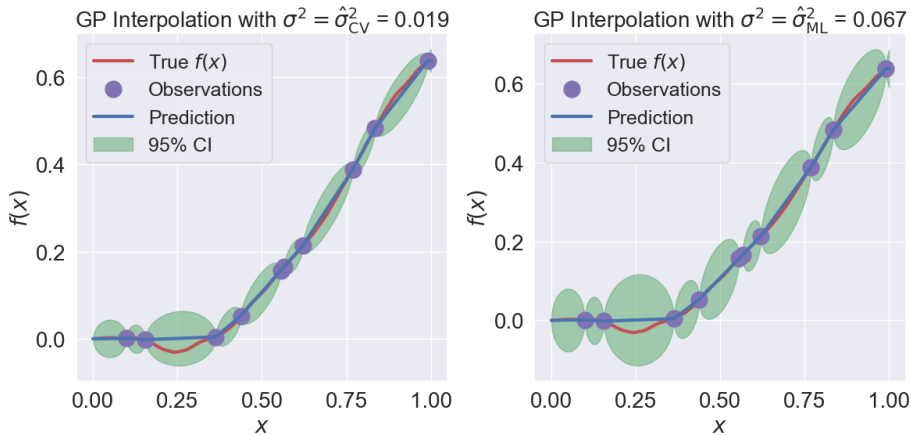


Figure 3: Left: with the CV estimator; Right: with the ML estimator.

Asymptotics of CV and ML Estimators ($1.5 < \ell + H < 2$)

Theorem (when $\ell = 1$ and $0.5 < H < 1$):

$$\mathbb{E}[\hat{\sigma}_{\text{CV}}^2] = \Theta(N^{-2}), \quad \mathbb{E}[\hat{\sigma}_{\text{ML}}^2] = \Theta(N^{-1}).$$

- CV also no longer adapts (while yielding tighter intervals than ML).
- These asymptotic rates of CV and ML have been empirically confirmed (for different smoothness settings); please see our paper if interested.

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Consequences to Credible Intervals

- For $\hat{\sigma} = \hat{\sigma}_{CV}$ or $\hat{\sigma} = \hat{\sigma}_{ML}$, a credible intervals may be given as

$$[m_N(x) - \alpha\hat{\sigma}\sqrt{k_N(x)}, \quad m_N(x) + \alpha\hat{\sigma}\sqrt{k_N(x)}].$$

(e.g., $\alpha \approx 1.96$ for a 95 % credible interval.)

- This interval is **asymptotically well-calibrated** if

$$|f(x) - m_N(x)| \quad \text{and} \quad \hat{\sigma}\sqrt{k_N(x)}$$

decrease to 0 as $N \rightarrow \infty$ at the **same rate**.

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decrease to 0 as $N \rightarrow \infty$ at the **same rate**.

- For CV and ML, can this hold? (and if so, when?)

- To study this question, we consider the ratio

$$\frac{|f(x) - m_N(x)|}{\hat{\sigma} \sqrt{k_N(x)}}.$$

- It is necessary that this **neither converge to 0 nor diverge to ∞** as $N \rightarrow \infty$.

Consequences to Credible Intervals ($0 < \ell + H < 1$)

- Recall that true f is assumed to be $f \sim \mathcal{GP}(0, k_{\ell, H})$ (smoothness $\ell + H$).

Theorem (when $\ell = 0$ and $0 < H < 1$)

$$\sup_{x \in [0, 1]} \frac{\mathbb{E}[f(x) - m_N(x)]^2}{\mathbb{E}\hat{\sigma}_{\text{CV}}^2 k_N(x)} = \Theta(1),$$

$$\sup_{x \in [0, 1]} \frac{\mathbb{E}[f(x) - m_N(x)]^2}{\mathbb{E}\hat{\sigma}_{\text{ML}}^2 k_N(x)} = \Theta(1),$$

- Both CV and ML are asymptotically well-calibrated (on average)

Consequences to Credible Intervals ($1 < \ell + H \leq 1.5$)

Theorem (when $\ell = 1$ and $0 < H \leq 1/2$)

$$\sup_{x \in [0,1]} \frac{\mathbb{E}[f(x) - m_N(x)]^2}{\mathbb{E}\hat{\sigma}_{\text{CV}}^2 k_N(x)} = \Theta(1),$$
$$\sup_{x \in [0,1]} \frac{\mathbb{E}[f(x) - m_N(x)]^2}{\mathbb{E}\hat{\sigma}_{\text{ML}}^2 k_N(x)} = \Theta(N^{-2H}),$$

- CV is asymptotically well-calibrated.
- ML is asymptotically **underconfident**.

Consequences to Credible Intervals ($1.5 < \ell + H < 2$)

Theorem (when $\ell = 1$ and $1/2 < H \leq 1$)

$$\sup_{x \in [0,1]} \frac{\mathbb{E}[f(x) - m_N(x)]^2}{\mathbb{E}\hat{\sigma}_{CV}^2 k_N(x)} = \Theta(N^{1-2H}),$$

$$\sup_{x \in [0,1]} \frac{\mathbb{E}[f(x) - m_N(x)]^2}{\mathbb{E}\hat{\sigma}_{ML}^2 k_N(x)} = \Theta(N^{-2H}),$$

- Both are asymptotically underconfident.
- The ratio decreases more slowly with CV than ML (CV is relatively less conservative).

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Conclusion and Future Directions

- Under specific settings (one-dimension, Brownian motion prior, scale parameter estimation), we have shown, for the first time, quantitatively that **the CV estimator is better than the ML estimator in terms of UQ.**
- Future work should study whether similar results hold in other settings (e.g., smoother priors, other hyperparameters, noisy observations).
- Other results (e.g., when the true function is deterministic) are also available in our paper:

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